

# TOSHIBA MACHINE



VERTICAL ARTICULATED ROBOT

## TVL/TV Series



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ISO14001

URL : <http://www.toshiba-machine.co.jp/en/product/robot/index.html>  
<http://www.toshiba-machine.com>  
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<http://www.tmrobotics.com>



Caution

Before operating the industrial robot, read through and completely understand the instruction manuals.

- The contents included in this catalog are subject to change without prior notice to reflect improvements.

**ELMOTEC**  
Automation | Löttechnik

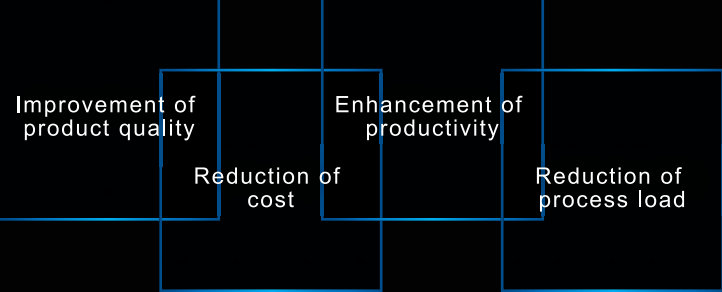


Brings overwhelming competitiveness to your production site

# VERTICAL ARTICULATED ROBOT TVL/TV Series

A vertical articulated robot allows flexible and three-dimensional motion similar to that of a human being. Based on advanced technologies cultivated with industrial machinery and plenty of expertise gained through a lot of experience of production sites, Toshiba Machine provides high-quality vertical articulated robots for improvement in customer productivity that attain high-speed capability, complete weight saving, and a lot of functionalities, and realize durability and expandability capable of being applied to a wide range of production environments.

Our articulated robots contribute to process automation, labor-saving, and cost reduction in a wide range of the fields including assembly of electronic equipment and inspection/carrying of food and medicinal products.

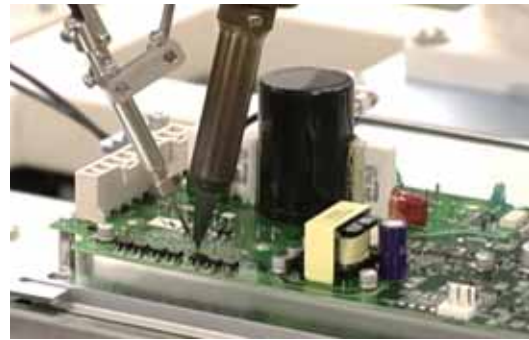




## Application examples of TVL/TV Series

### Application examples in our manufacturing sites

Examples of automation in our manufacturing sites using cell production robots



#### Soldering process

The robot enables stable soldering that produces high quality products efficiently.

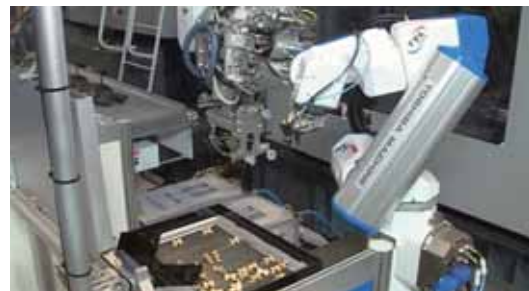


#### Screw tightening process

Sensorless compliance control technologies is utilized in screw tightening.

## Examples of injection molding machine systems

Toshiba Machine has accumulated many automation system examples and considerable understanding of corporation between injection molding machines and robots.



Supply of metal nut parts for insert molding



Thickness measurement and appearance inspection of a 10.1-inch thin light guide plate



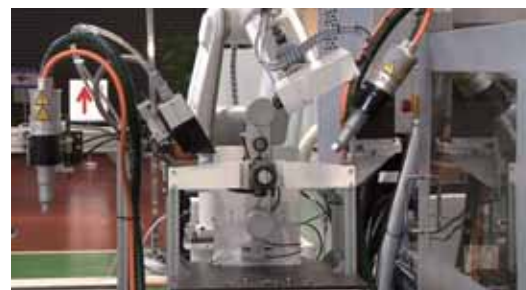
Sprue cutting of a CF RTP molded item



Picking up of a C(G)FRTP hybrid molded item



Inserting of a semfinished laminated lens product



Print decorating in a decoration system

Low-cost robot with top-class performance  
Highly cost-effective compact model

## Vertical articulated robot TVL Series

The TVL Series robot achieves high productivity in assembling and transfer processes in small spaces, combining top-class performance with low cost for superior cost effectiveness. A variety of options for convenience and the enhancement of workability, plus suitability for a wide range of work environments, are available.



### World-class performance

(standard cycle time of less than 0.4 seconds)

### Special features

#### Tap holes

Tool fixture tap holes are provided at four locations on the arm, upper and lower positions. They are useful for fixing external cabling and peripheral devices.



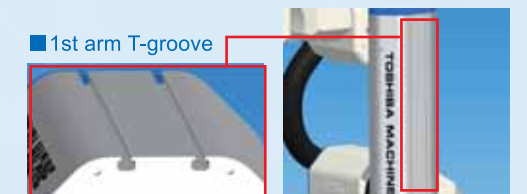
#### Alternative installations

Tap holes on the side of the base unit allow for the robot to be installed sideways. This reduces the need for installation space.



#### 1st arm equipped with a T-groove as standard

The T-groove can be used to place tools, cabling and DIN rails in position.



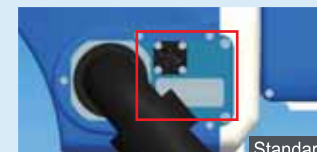
### Variety of options

#### I/O panel options

The I/O panel can be selected from three options.

An optional elbow type plug is available on the hand-side connection. Optional

##### The second arm side



Standard

##### The second arm top surface



Optional

##### The third arm side



Optional

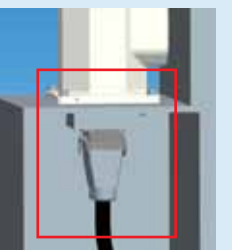
##### Hand side connector elbow type



Optional

#### Robot controller cable options

In addition to the standard cabling at the back, cabling can be routed through the base. This eliminates the need for installation space at the rear, and increases flexibility relating to the application and the space available.



#### IP65 option

Dust-proof and drip-proof protection is available.

### Compact controller

Controller TSL3100 specifically designed for the vertical articulated robot.

For details, refer to page 11.



Teach pendant Optional

TSL3100

TP1000-6ax

TP3000



World-class performance  
(standard cycle time of less than 0.4 seconds)

# TVL500



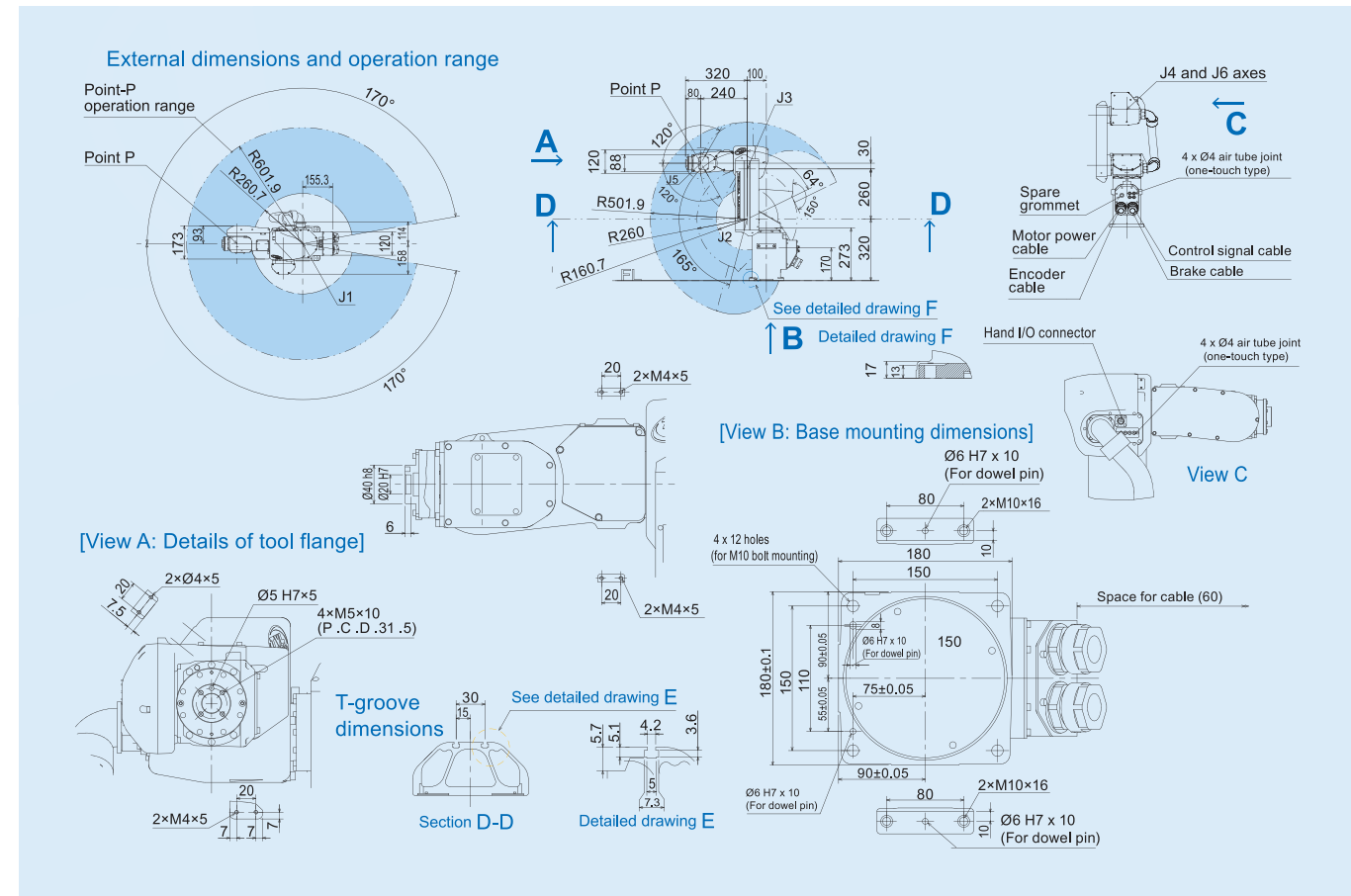
- Arm length 500 mm
- Maximum payload mass 3 kg
- Standard cycle time 0.3 sec level
- IP65 option

## Specifications

| Model                                | TVL500                       |                           |
|--------------------------------------|------------------------------|---------------------------|
| Type                                 | Vertically articulated robot |                           |
| Number of controlled axis            | 6 axes                       |                           |
| Arm length                           | Total length                 | 500 mm                    |
|                                      | 1st arm                      | 260 mm                    |
|                                      | 2nd arm                      | 240 mm                    |
|                                      | Reach                        | 602 mm                    |
| Working envelope                     | Axis 1 (J1)                  | ±170°                     |
|                                      | Axis 2 (J2)                  | -64~+165°                 |
|                                      | Axis 3 (J3)                  | 0~+150°                   |
|                                      | Axis 4 (J4)                  | ±190°                     |
|                                      | Axis 5 (J5)                  | ±120°                     |
|                                      | Axis 6 (J6)                  | ±360°                     |
| Maximum speed *1                     | Axis 1 (J1)                  | 435°/s                    |
|                                      | Axis 2 (J2)                  | 348°/s                    |
|                                      | Axis 3 (J3)                  | 348°/s                    |
|                                      | Axis 4 (J4)                  | 422°/s                    |
|                                      | Axis 5 (J5)                  | 422°/s                    |
|                                      | Axis 6 (J6)                  | 696°/s                    |
|                                      | Composite *2                 | 7.98 m/sec                |
| Maximum payload mass *1              |                              | 3 kg (rated: 1 kg)        |
|                                      |                              | (Downward: 5 kg)          |
| Standard cycle time *3               | 0.3 sec level                |                           |
| Allowable moment of inertia *1       | Axis 4, 5                    | 0.15 kg·m <sup>2</sup>    |
|                                      | Axis 6                       | 0.2 kg·m <sup>2</sup>     |
| Positioning repeatability (X-Y-Z) *4 |                              | ±0.02 mm (each direction) |
| Driving system                       |                              | AC servo motors           |
| Power supply                         |                              | 1.5 kVA                   |
| Robot body                           | Mass                         | 28 kg                     |
|                                      | Color *5                     | White/blue                |

\*1: Acceleration rates are limited depending on motion patterns, payload mass, and offset value.  
\*2: Under rated load  
\*3: Continuous operation of standard cycle motion pattern is not possible beyond the effective load ratio. (Horizontal 300 mm, vertical 25 mm, round-trip, coarse positioning)  
\*4: When the environment temperature is constant.  
\*5: Color and surface treatment of the robot body may vary slightly for each production batch. This causes no problem with the product quality.

## External view



Dealing with a wide range of needs in assembling and transfer processes while realizing high cost effectiveness.

# TVL700



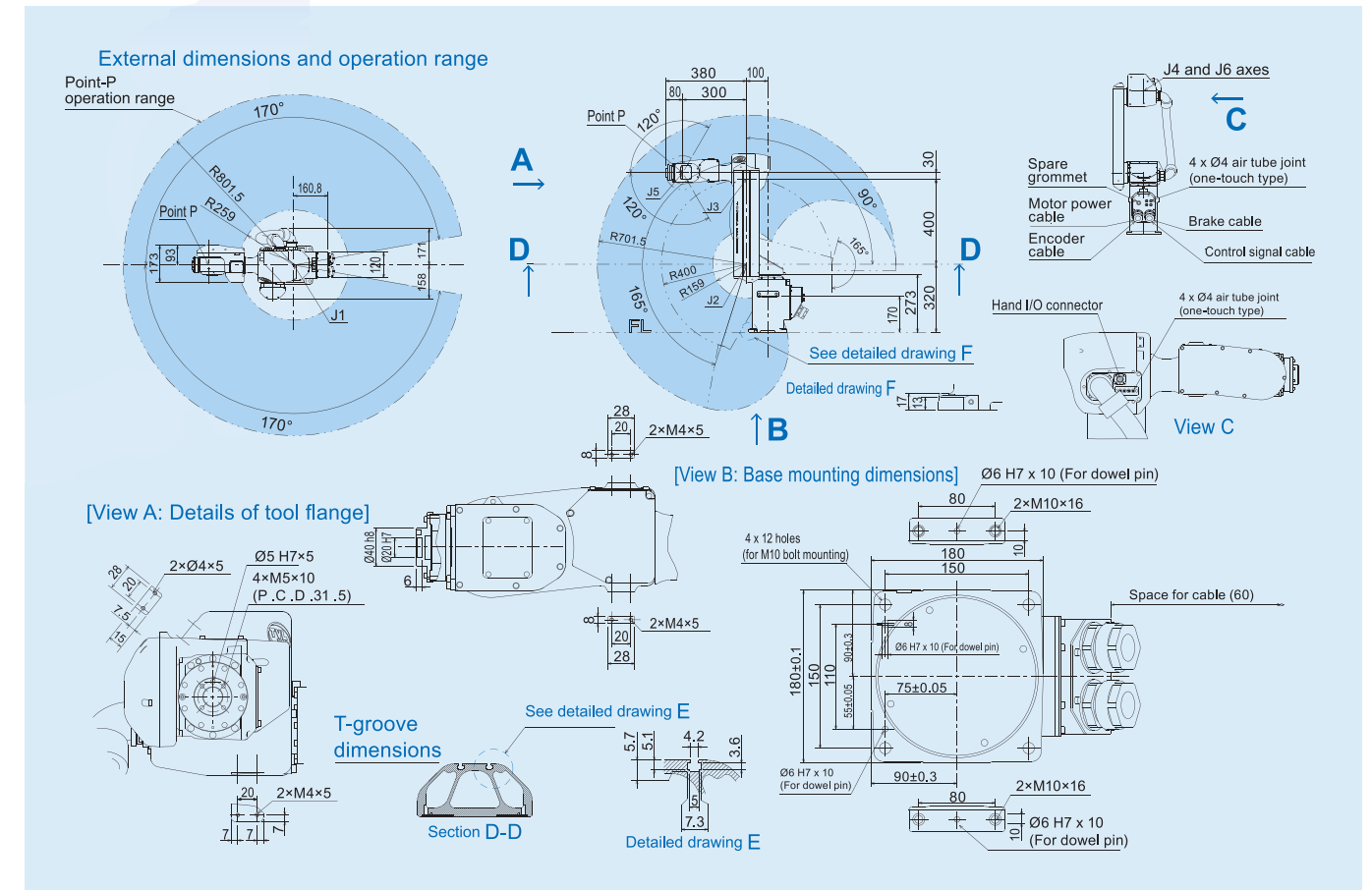
- Arm length 700 mm
- Maximum payload mass 4 kg
- Standard cycle time 0.4 sec level
- IP65 option

## Specifications

| Model                                | TVL700                       |                           |
|--------------------------------------|------------------------------|---------------------------|
| Type                                 | Vertically articulated robot |                           |
| Number of controlled axis            | 6 axes                       |                           |
| Arm length                           | Total length                 | 700 mm                    |
|                                      | 1st arm                      | 400 mm                    |
|                                      | 2nd arm                      | 300 mm                    |
|                                      | Reach                        | 801 mm                    |
| Working envelope                     | Axis 1 (J1)                  | ±170°                     |
|                                      | Axis 2 (J2)                  | -90~+165°                 |
|                                      | Axis 3 (J3)                  | 0~+165°                   |
|                                      | Axis 4 (J4)                  | ±190°                     |
|                                      | Axis 5 (J5)                  | ±120°                     |
|                                      | Axis 6 (J6)                  | ±360°                     |
| Maximum speed *1                     | Axis 1 (J1)                  | 295°/s                    |
|                                      | Axis 2 (J2)                  | 270°/s                    |
|                                      | Axis 3 (J3)                  | 295°/s                    |
|                                      | Axis 4 (J4)                  | 422°/s                    |
|                                      | Axis 5 (J5)                  | 422°/s                    |
|                                      | Axis 6 (J6)                  | 696°/s                    |
|                                      | Composite *2                 | 7.71 m/sec                |
| Maximum payload mass *1              |                              | 4 kg (rated: 1 kg)        |
|                                      |                              | (Downward: 5 kg)          |
| Standard cycle time *3               | 0.4 sec level                |                           |
| Allowable moment of inertia *1       | Axis 4, 5                    | 0.09 kg·m <sup>2</sup>    |
|                                      | Axis 6                       | 0.1 kg·m <sup>2</sup>     |
| Positioning repeatability (X-Y-Z) *4 |                              | ±0.03 mm (each direction) |
| Driving system                       |                              | AC servo motors           |
| Power supply                         |                              | 1.5 kVA                   |
| Robot body                           | Mass                         | 31 kg                     |
|                                      | Color *5                     | White/blue                |

\*1: Acceleration rates are limited depending on motion patterns, payload mass, and offset value.  
\*2: Under rated load  
\*3: Continuous operation of standard cycle motion pattern is not possible beyond the effective load ratio. (Horizontal 300 mm, vertical 25 mm, round-trip, coarse positioning)  
\*4: When the environment temperature is constant.  
\*5: Color and surface treatment of the robot body may vary slightly for each production batch. This causes no problem with the product quality.

## External view





High-end robot with high speed and high rigidity

# Vertical articulated robot TV Series

Excellent rigidity, durability, and expandability.  
Superior operability with due easy to use software.  
Compliance control using no force sensor.  
Elimination of necessity for external sensors allows force control at a low cost.

Excellent rigidity

Excellent durability

Excellent expandability

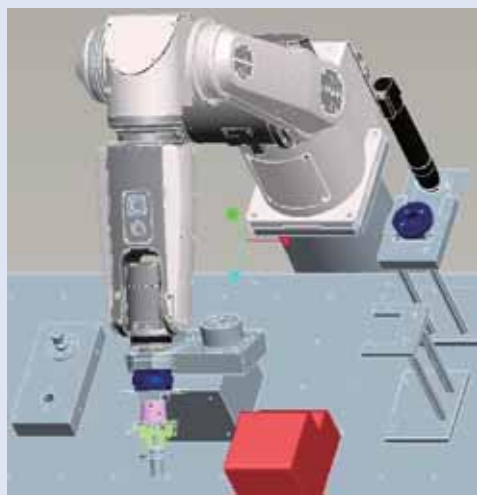


Capable of inserting and achieving compliance actions without force sensor (sensorless compliance control)

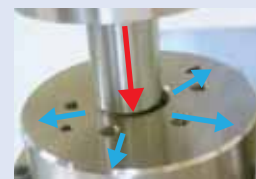
Automation of processes that require force control can be realized without force sensors.

## What is the sensorless compliance control?

The TV Series robot attains compliance control without using force sensors. Misalignment is absorbed by the flexible hand with the control that can adjust the force. As a result, stable work processes with less temporary stops can be realized.



### Examples of work process



#### 1 Inserting process

Smooth insertion is realized by loosening horizontal force while pushing vertically with constant insertion force.



#### 2 Pin hole searching process

Even when a hole position cannot be figured out exactly, the robot can find it by turning the wrist while pushing vertically.



#### 3 Screwing process

Synchronization with the screw feed rate is unnecessary. Stable screwing without sticking or failure of a screw can be performed by screwing while pushing vertically with constant force.

## High-performance controller

Controller TS3100 specifically designed for the vertical articulated robot.

For details, refer to page 12.



Teach pendant **Optional**



Compact and light-weight robot that can be introduced into production facilities with ease.  
Suitable for assembling work such as fitting processes due to the flexible hand control.

# TV600



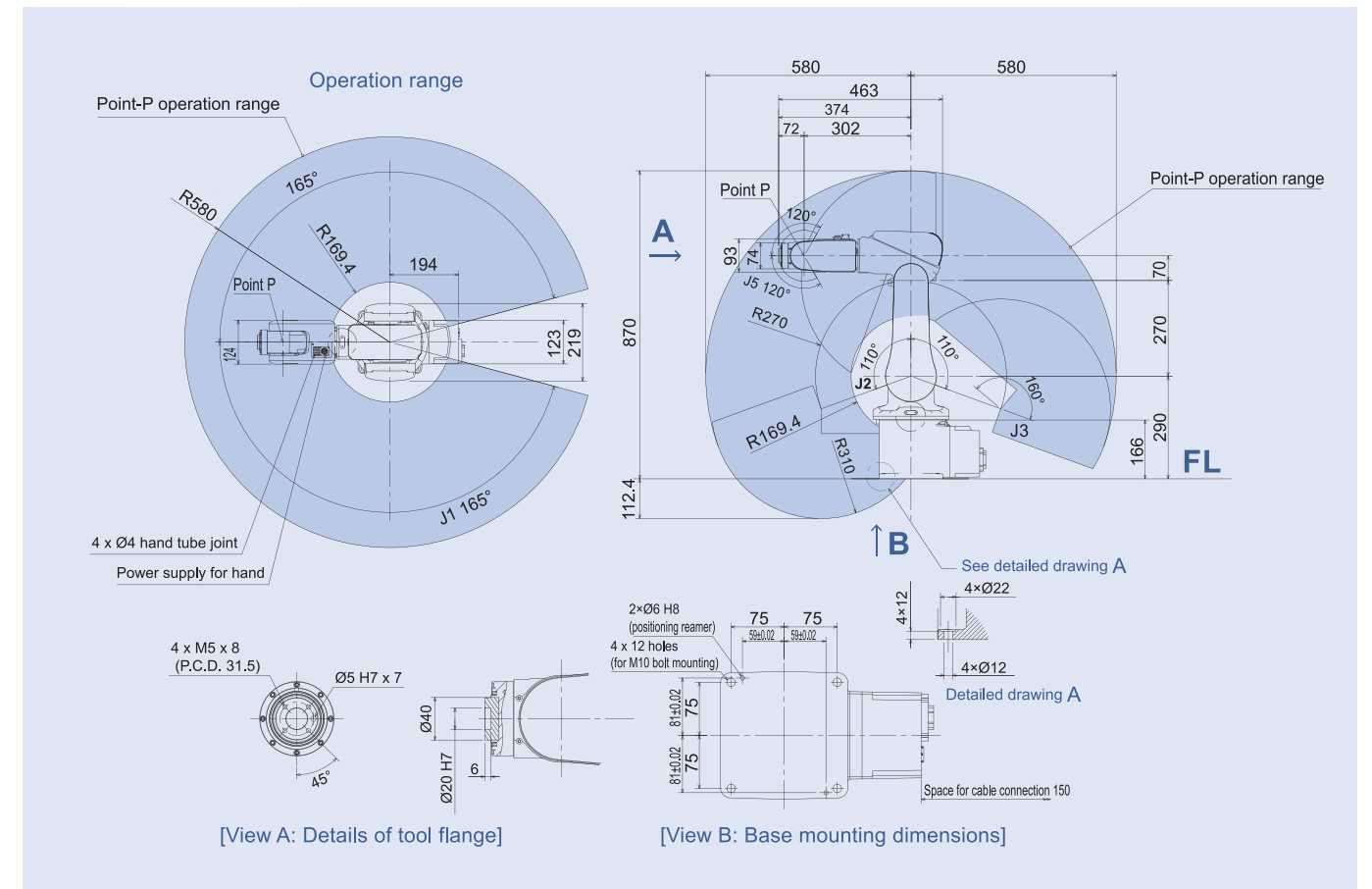
- Arm length 572 mm
- Maximum payload mass 3 kg
- Compact and light-weight
- User friendly software

### Specifications

| Model                                | TV600                        |                         |
|--------------------------------------|------------------------------|-------------------------|
| Type                                 | Vertically articulated robot |                         |
| Number of controlled axis            | 6 axes                       |                         |
| Arm length                           | Total length                 | 572 mm                  |
|                                      | 1st arm                      | 270 mm                  |
|                                      | 2nd arm                      | 302 mm                  |
|                                      | Reach                        | 580 mm                  |
| Working envelope                     | Axis 1 (J1)                  | ±165°                   |
|                                      | Axis 2 (J2)                  | +110°                   |
|                                      | Axis 3 (J3)                  | 0→+160°                 |
|                                      | Axis 4 (J4)                  | ±160°                   |
|                                      | Axis 5 (J5)                  | ±120°                   |
|                                      | Axis 6 (J6)                  | ±400°                   |
| Maximum speed *1                     | Axis 1 (J1)                  | 250°/s                  |
|                                      | Axis 2 (J2)                  | 250°/s                  |
|                                      | Axis 3 (J3)                  | 250°/s                  |
|                                      | Axis 4 (J4)                  | 320°/s                  |
|                                      | Axis 5 (J5)                  | 320°/s                  |
|                                      | Axis 6 (J6)                  | 420°/s                  |
|                                      | Composite *2                 | 5.9 m/sec               |
| Maximum payload mass *1              |                              | 3 kg (rated: 1 kg)      |
|                                      |                              | (Downward: 5 kg)        |
| Standard cycle time *3               | 0.58 sec level               |                         |
| Allowable moment of inertia *1       | Axis 4, 5                    | 0.02 kg·m <sup>2</sup>  |
|                                      | Axis 6                       | 0.015 kg·m <sup>2</sup> |
| Positioning repeatability (X-Y-Z) *4 | ±0.03 mm (each direction)    |                         |
| Driving system                       | AC servo motors              |                         |
| Power supply                         | 1.0 kVA                      |                         |
| Robot body                           | Mass                         | 25 kg                   |
|                                      | Color *5                     | White                   |

\*1: Acceleration rates are limited depending on motion patterns, payload mass, and offset value.  
\*2: Under rated load  
\*3: Continuous operation of standard cycle motion pattern is not possible beyond the effective load ratio. (Horizontal 300 mm, vertical 25 mm, round-trip, coarse positioning)  
\*4: When the environment temperature is constant.  
\*5: Color and surface treatment of the robot body may vary slightly for each production batch. This causes no problem with the product quality.

### External view





Plenty of options available for various environments.  
Applicable to a wide range of needs including production lines and assembly processes

# TV800



- Arm length 800 mm
- Maximum payload mass 5 kg
- Standard cycle time 0.4 sec level

### Optional

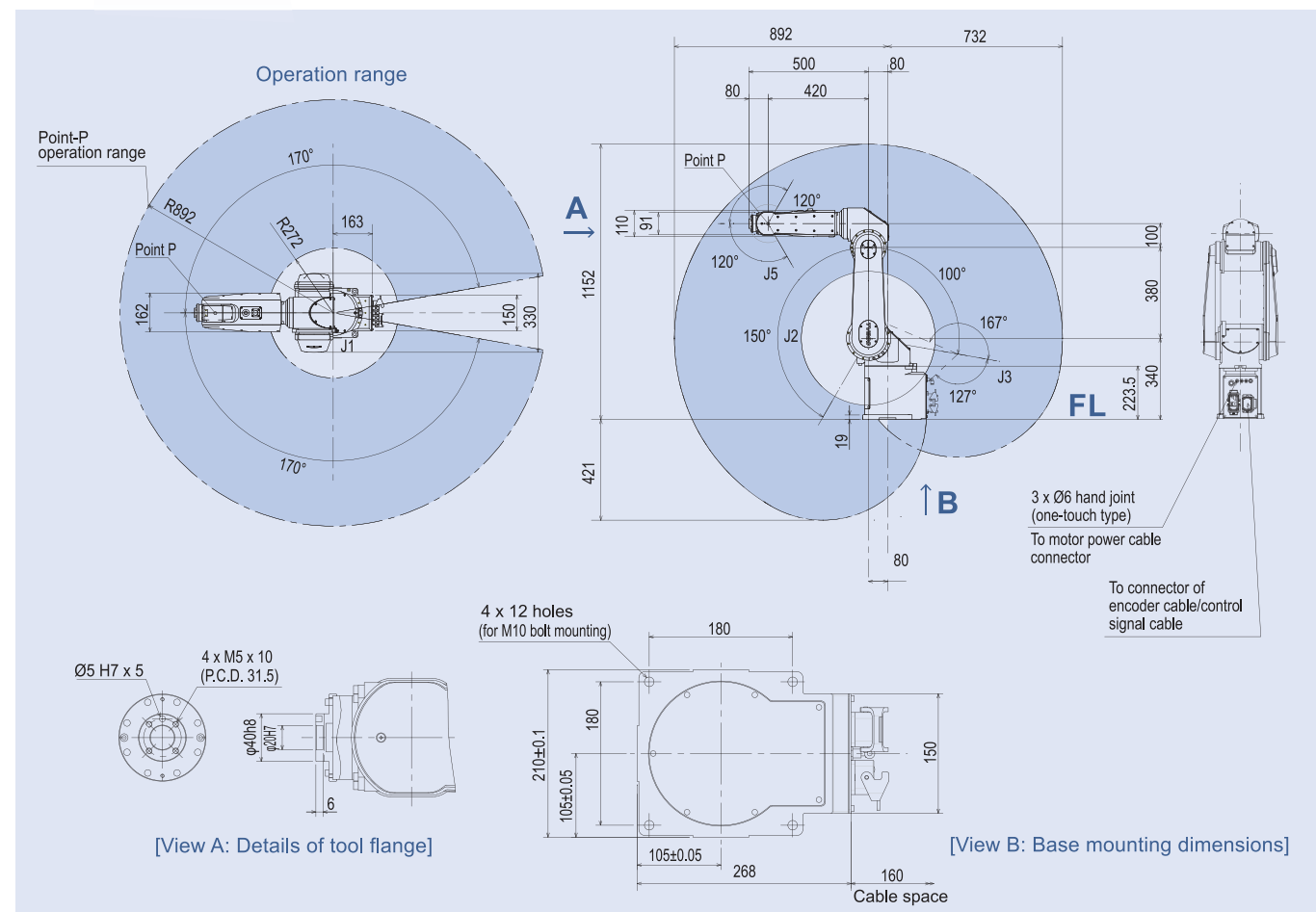
- Dust and drip proof (IP65)
- Clean
- Safety category 3
- Ceiling mount

### Specifications

| Model   | TV800                        |                          |
|---|------------------------------|--------------------------|
| Type  | Vertically articulated robot |                          |
| Number of controlled axis                       | 6 axes                       |                          |
| Arm length                                      | Total length                 | 800 mm                   |
|   | 1st arm                      | 380 mm                   |
|   | 2nd arm                      | 420 mm                   |
|   | Reach                        | 892 mm                   |
| Working envelope                                | Axis 1 (J1)                  | ±170°                    |
|   | Axis 2 (J2)                  | -100~+150°               |
|   | Axis 3 (J3)                  | -127~+167°               |
|   | Axis 4 (J4)                  | ±190°                    |
|   | Axis 5 (J5)                  | ±120°                    |
|   | Axis 6 (J6)                  | ±360°                    |
| Maximum speed <sup>*1</sup>                     | Axis 1 (J1)                  | 237°/s                   |
|   | Axis 2 (J2)                  | 240°/s                   |
|   | Axis 3 (J3)                  | 288°/s                   |
|   | Axis 4 (J4)                  | 350.5°/s                 |
|   | Axis 5 (J5)                  | 484°/s                   |
|   | Axis 6 (J6)                  | 576°/s                   |
| Composite <sup>*2</sup>                         | 8.06 m/sec                   |                          |
| Maximum payload mass <sup>*1</sup>              | 5 kg                         |                          |
| Standard cycle time <sup>*3</sup>               | 0.4 sec level                |                          |
| Allowable moment of inertia <sup>*1</sup>       | Axis 4, 5                    | 0.3 kg · m <sup>2</sup>  |
|   | Axis 6                       | 0.05 kg · m <sup>2</sup> |
| Positioning repeatability (X-Y-Z) <sup>*4</sup> | ±0.02 mm (each direction)    |                          |
| Driving system                                  | AC servo motors              |                          |
| Robot body                                      | Mass                         | 45 kg                    |
|   | Color <sup>*5</sup>          | White/Light gray         |

<sup>\*1</sup>: Acceleration rates are limited depending on motion patterns, payload mass, and offset value.  
<sup>\*2</sup>: Under rated load  
<sup>\*3</sup>: Continuous operation of standard cycle motion pattern is not possible beyond the effective load ratio. (Horizontal 300 mm, vertical 25 mm, round-trip, coarse positioning)  
<sup>\*4</sup>: When the environment temperature is constant.  
<sup>\*5</sup>: Color and surface treatment of the robot body may vary slightly for each production batch. This causes no problem with the product quality.

### External view



Plenty of options available for various environments.  
Lightest robot in class.

# TV1000



- Arm length 1000 mm
- Maximum payload mass 5 kg
- Standard cycle time 0.6 sec level

### Optional

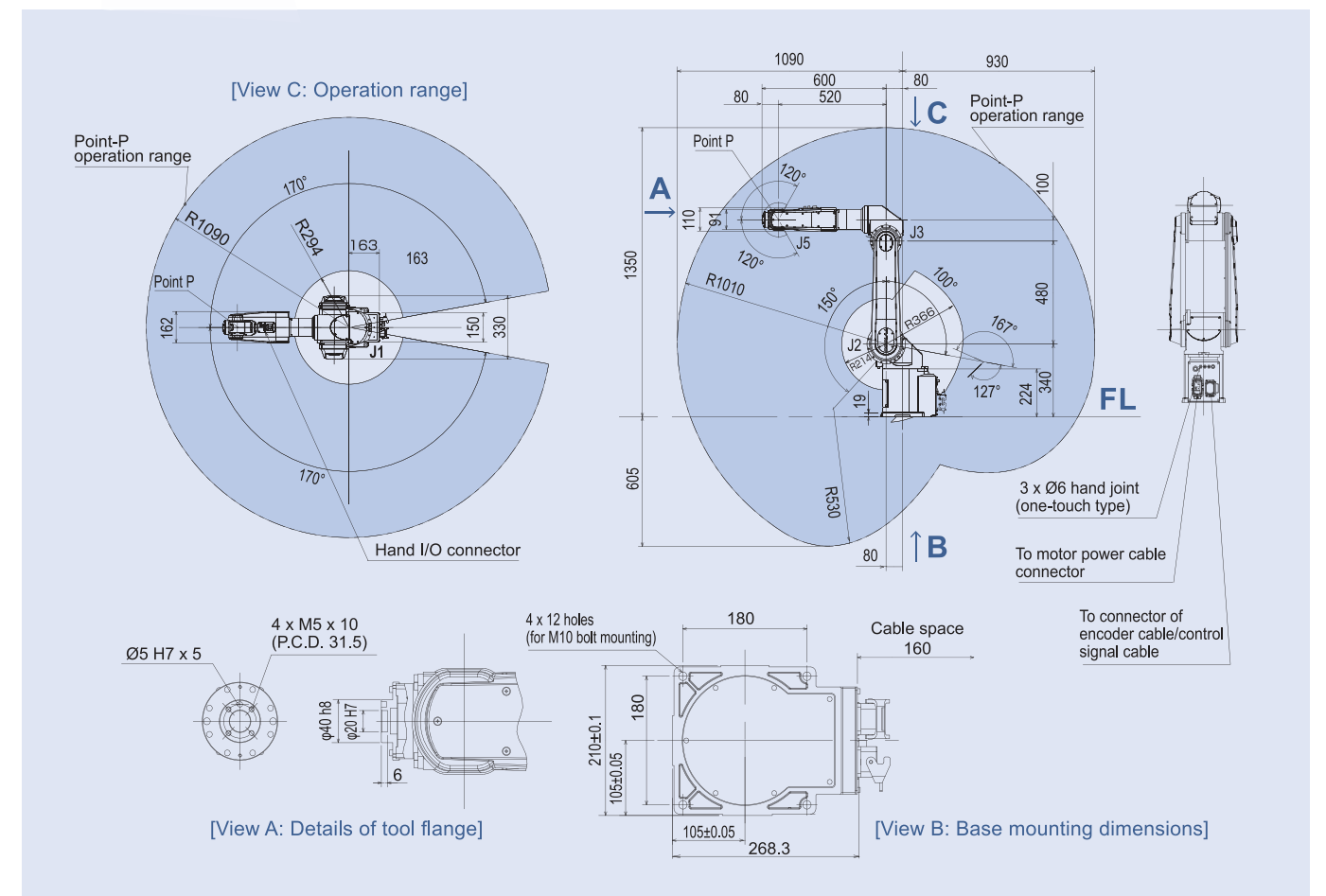
- Payload mass 10 kg (TV1000H)
- Dust and water proof (IP67)
- \* only for wrist of TV1000H
- Dust and drip proof (IP65)
- Clean
- Safety category 3
- Ceiling mount

### Specifications

| Model   | TV1000                       |                          |
|---|------------------------------|--------------------------|
| Type  | Vertically articulated robot |                          |
| Number of controlled axis                       | 6 axes                       |                          |
| Arm length                                      | Total length                 | 1000 mm                  |
|   | 1st arm                      | 480 mm                   |
|   | 2nd arm                      | 520 mm                   |
|   | Reach                        | 1090 mm                  |
| Working envelope                                | Axis 1 (J1)                  | ±170°                    |
|   | Axis 2 (J2)                  | -100~+150°               |
|   | Axis 3 (J3)                  | -127~+167°               |
|   | Axis 4 (J4)                  | ±190°                    |
|   | Axis 5 (J5)                  | ±120°                    |
|   | Axis 6 (J6)                  | ±360°                    |
| Maximum speed <sup>*1</sup>                     | Axis 1 (J1)                  | 237°/s                   |
|   | Axis 2 (J2)                  | 240°/s                   |
|   | Axis 3 (J3)                  | 288°/s                   |
|   | Axis 4 (J4)                  | 350.5°/s                 |
|   | Axis 5 (J5)                  | 484°/s                   |
|   | Axis 6 (J6)                  | 576°/s                   |
| Composite <sup>*2</sup>                         | 9.61 m/sec                   |                          |
| Maximum payload mass <sup>*1</sup>              | 5 kg                         |                          |
| Standard cycle time <sup>*3</sup>               | 0.6 sec level                |                          |
| Allowable moment of inertia <sup>*1</sup>       | Axis 4, 5                    | 0.3 kg · m <sup>2</sup>  |
|   | Axis 6                       | 0.05 kg · m <sup>2</sup> |
| Positioning repeatability (X-Y-Z) <sup>*4</sup> | ±0.03 mm (each direction)    |                          |
| Driving system                                  | AC servo motors              |                          |
| Robot body                                      | Mass                         | 47 kg                    |
|   | Color <sup>*5</sup>          | White/Light gray         |

<sup>\*1</sup>: Acceleration rates are limited depending on motion patterns, payload mass, and offset value.  
<sup>\*2</sup>: Under rated load  
<sup>\*3</sup>: Continuous operation of standard cycle motion pattern is not possible beyond the effective load ratio. (Horizontal 300 mm, vertical 25 mm, round-trip, coarse positioning)  
<sup>\*4</sup>: When the environment temperature is constant.  
<sup>\*5</sup>: Color and surface treatment of the robot body may vary slightly for each production batch. This causes no problem with the product quality.

### External view





# Controllers and teach pendants specifically designed for the vertical articulated robot

For TVL Series

## TSL3100

Cost effective compact controller



For TVL Series

NEW

## TSL3100E

Low-cost and compact CE compliant controller

CE compliant



For all TVL Series robots

Teach pendant **Optional**

## TP1000-6ax

Standard teach pendant

## TP3000

Teach pendant equipped with graphic operation keys



TP1000-6ax



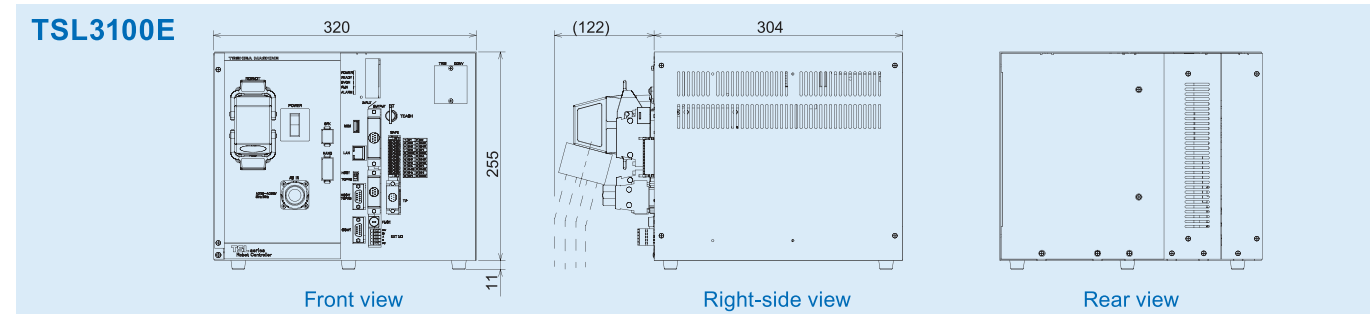
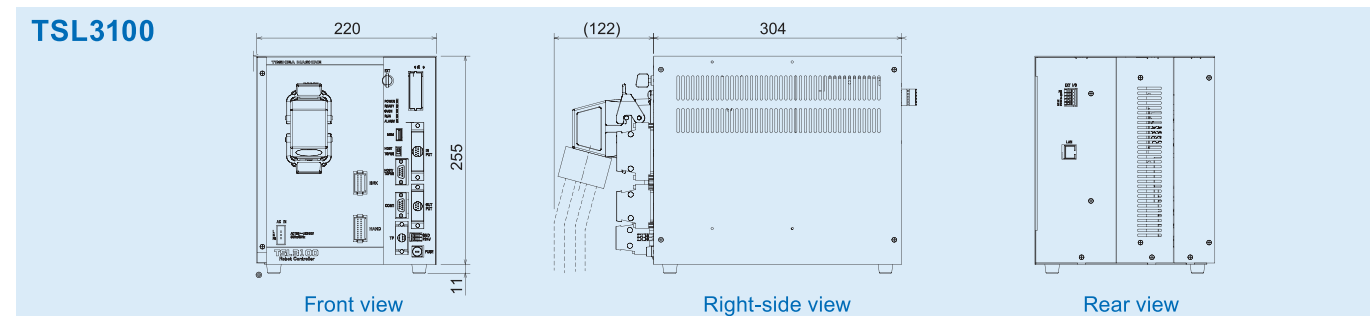
TP3000

### Specifications

| Model  | TSL3100   | TSL3100E  |
|--|---|---|
| Number of controlled axes                    | Maximum 6 axes  | Maximum 6 axes  |
| Motion modes                                 | PTP, CP (Continuous Path; Linear, Circular), Short-Cut  | PTP, CP (Continuous Path; Linear, Circular), Short-Cut  |
| Storage capacity                             | Approx. Total: 6400 point + 12800 steps<br>1 program: 2000 point + 3000 steps   | Approx. Total: 6400 point + 12800 steps<br>1 program: 2000 point + 3000 steps   |
| Number of registerable programs              | Maximum 256   | Maximum 256   |
| Programming language                         | SCOL (similar to BASIC)   | SCOL (similar to BASIC)   |
| Teach pendant (optional)                     | Teach pendants TP3000 and TP1000-6ax (Program can also be written on PC)  | Teach pendants TP3000 and TP1000-6ax (Program can also be written on PC)  |
| Extended I/O signals                         | 8 inputs / 8 outputs  | 8 inputs / 8 outputs  |
| Hand control signals                         | 8 inputs / 8 outputs  | 8 inputs / 8 outputs  |
| External operation signals                   | Input: cycle operation mode, start, stop, etc. (13 signals)<br>Output: Servo ON, emergency stop, etc. (11 signals)                | Input: cycle operation mode, start, stop, etc. (13 signals)<br>Output: External mode, automatic operation, etc. (9 signals)       |
| Communication port                           | RS232C: 2 ports, Ethernet*, USB   | RS232C: 2 ports, Ethernet*, USB   |
| Other functions                              | Interruptive functions, self-diagnosis, I/O control and communications during motion, coordinate calculations, built-in PLC, etc. | Interruptive functions, self-diagnosis, I/O control and communications during motion, coordinate calculations, built-in PLC, etc. |
| Power supply                                 | Single phase AC190 V to 240 V, 50/60 Hz   | Single phase AC190 V to 240 V, 50/60 Hz   |
| Outer dimensions and mass                    | 220(W) x 266(H) x 304(D) [mm], 9 kg (including rubber feet)   | 320(W) x 266(H) x 304(D) [mm], 13 kg (including rubber feet)  |
| PC software for programming support (option) | TSPC: Program editor, teaching, remote operation, etc.  | TSPC: Program editor, teaching, remote operation, etc.  |
| I/O and Fieldbus options                     | I/O extension, I/O cable, Field-network (CC-Link, DeviceNet, PROFIBUS)*   | I/O extension, I/O cable, Field-network (CC-Link, DeviceNet, PROFIBUS)*, Conveyor synchronization, Trigger input                  |

\* CC-Link is a registered trademark of Mitsubishi Electric Corporation, DeviceNet is a registered trademark of ODVA, PROFIBUS is a registered trademark of Profibus User Organization, Ethernet is a registered trademark of Fuji Xerox Co., Ltd.

### External view



For TV600

## TS3100V2

Controller for vertical articulated robot TV600 with up to six axes simultaneous control.



For all TV Series robots

Teach pendant **Optional**

## TP1000-6ax

Standard teach pendant

## TP3000

Teach pendant equipped with graphic operation keys



TP1000-6ax



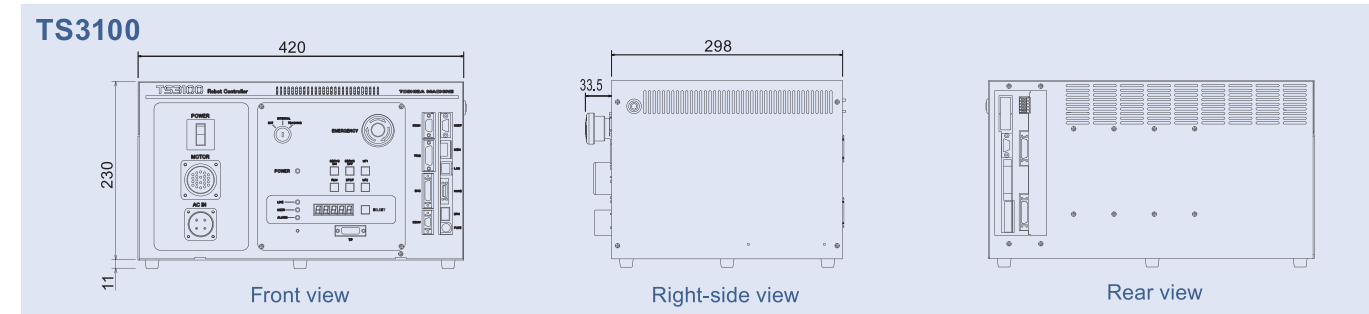
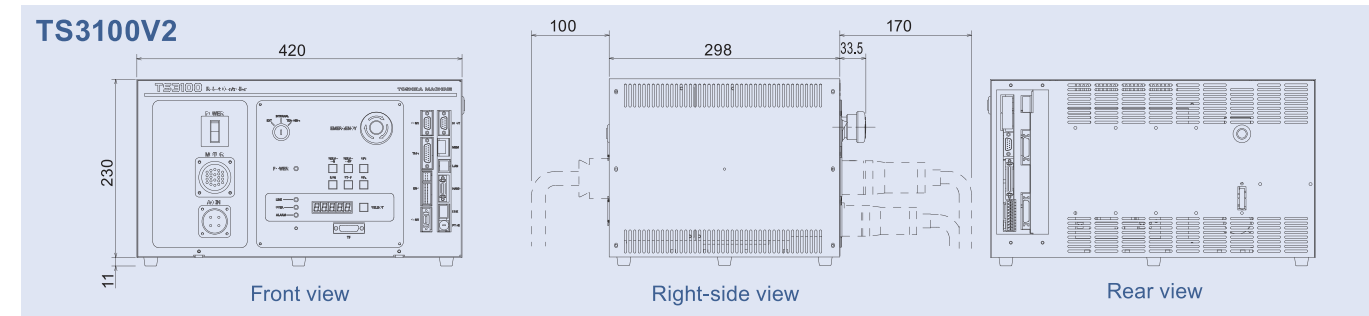
TP3000

### Specifications

| Model  | TS3100V2  | TS3100  |
|--|---|---|
| Number of controlled axes                    | Maximum 6 axes  | Maximum 6 axes  |
| Motion modes                                 | PTP, CP (Continuous Path; Linear, Circular), Short-Cut  | PTP, CP (Continuous Path; Linear, Circular), Short-Cut, Arch motion   |
| Storage capacity                             | Approx. Total: 12800 point + 25600 steps<br>1 program: 2000 point + 3000 steps  | Approx. Total: 12800 point + 25600 steps<br>1 program: 2000 point + 3000 steps  |
| Number of registerable programs              | Maximum 256   | Maximum 256   |
| Programming language                         | SCOL (similar to BASIC)   | SCOL (similar to BASIC)   |
| Teach pendant (optional)                     | Teach pendant with 5 m cable (Program can also be written on PC)  | Teach pendants TP1000 and TP3100 (Program can also be written on PC)  |
| Extended I/O signals                         | 32 inputs / 32 outputs  | 32 inputs / 32 outputs  |
| Hand control signals                         | 4 inputs / 4 outputs  | 8 inputs / 8 outputs  |
| External operation signals                   | Input: program selection, start, stop, program reset, etc.<br>Output: Servo ON, ready for operation, failure, cycle stop, etc.                  | Input: cycle operation mode, start, stop, reset, etc.<br>Output: Servo ON, ready for operation, failure, etc.                                   |
| Communication port                           | RRS232C: 2 ports, Ethernet*: 1 port, USB  | RS232C: 2 ports, Ethernet*: 1 port, USB   |
| Other functions                              | Torque limit, Interruptive functions, self-diagnosis, I/O control and communications during motion, coordinate calculations, built-in PLC, etc. | Torque limit, Interruptive functions, self-diagnosis, I/O control and communications during motion, coordinate calculations, built-in PLC, etc. |
| Power supply                                 | Single phase AC200 V to 240 V, 50/60 Hz   | Single phase AC200 V to 240 V, 50/60 Hz   |
| Outer dimensions and mass                    | 420(W) x 230(H) x 298(D) [mm], approximately 17 kg  | 420(W) x 230(H) x 298(D) [mm], approximately 17 kg  |
| PC software for programming support (option) | TSPC: Program editor, teaching, remote operation, etc.  | TSPC: Program editor, teaching, remote operation, etc.  |
| I/O and Fieldbus options                     | I/O extension, I/O cable, Field-network (CC-Link, DeviceNet, PROFIBUS)*   | I/O extension, I/O cable, Field-network (CC-Link, DeviceNet, PROFIBUS)*   |

\* CC-Link is a registered trademark of Mitsubishi Electric Corporation, DeviceNet is a registered trademark of ODVA, PROFIBUS is a registered trademark of Profibus User Organization, Ethernet is a registered trademark of Fuji Xerox Co., Ltd.

### External view





## Various functions to support the operation

Options and functions that maximize the robot performance and PC software for efficient robot system building.

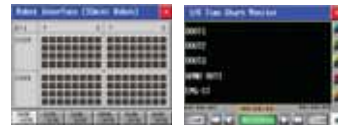
### Support for Sample Projects

**TOSHIBA MACHINE** × **Pro-face**  
for the best interface

Sample Projects are a collaborative system between Toshiba Machine Co., Ltd. and Digital Electronics Corporation. They enable users to check the status of the robot on the touch panel display device.

#### [Features and Advantages]

- When an error occurs in the robot, the error information or details can be checked on the Alarm Monitor Screen (see the below figure).
- Additionally, various other screens for functions including Robot I/O Monitor, Current Position Monitor, I/O Time Chart and Connected Device Data Transfer are provided.



- The above robot screens can be downloaded from the website of Digital Electronics Corporation free of charge. There is no need to create these screens and they can be used immediately after product purchase.

<http://www.pro-face.com/otasuke/download/sample/manufactures.html>

- The status of the robot can be checked even by people who cannot operate the teach pendant.
- Because the information about both the robot and the system is displayed on the same display device, troubleshooting is much easier.

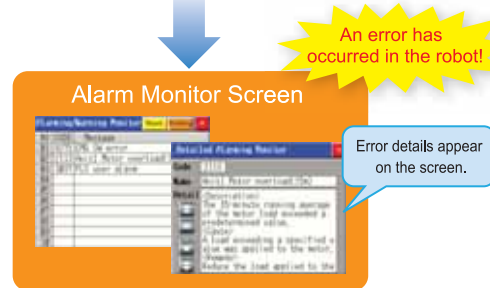
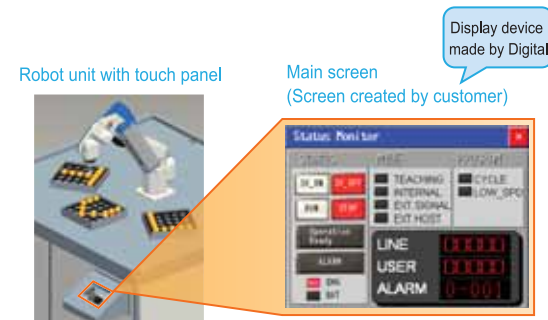
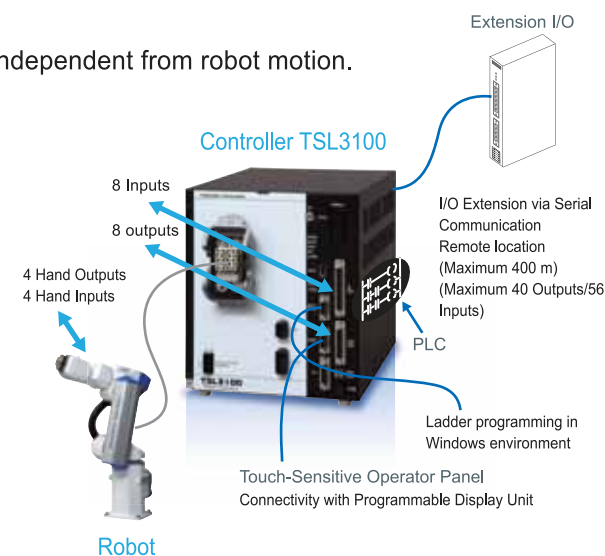
\*For product information about the touch panel that is compatible with this system, please contact Digital Electronics Corporation.  
[http://www.pro-face.com/otasuke/sample/detail/common/connection\\_robot\\_con\\_ts\\_e.html](http://www.pro-face.com/otasuke/sample/detail/common/connection_robot_con_ts_e.html)

### Built-In PLC

The robot controller has a built-in PLC (TCmini). Input and output signals can be controlled by a ladder program, independent from robot motion.

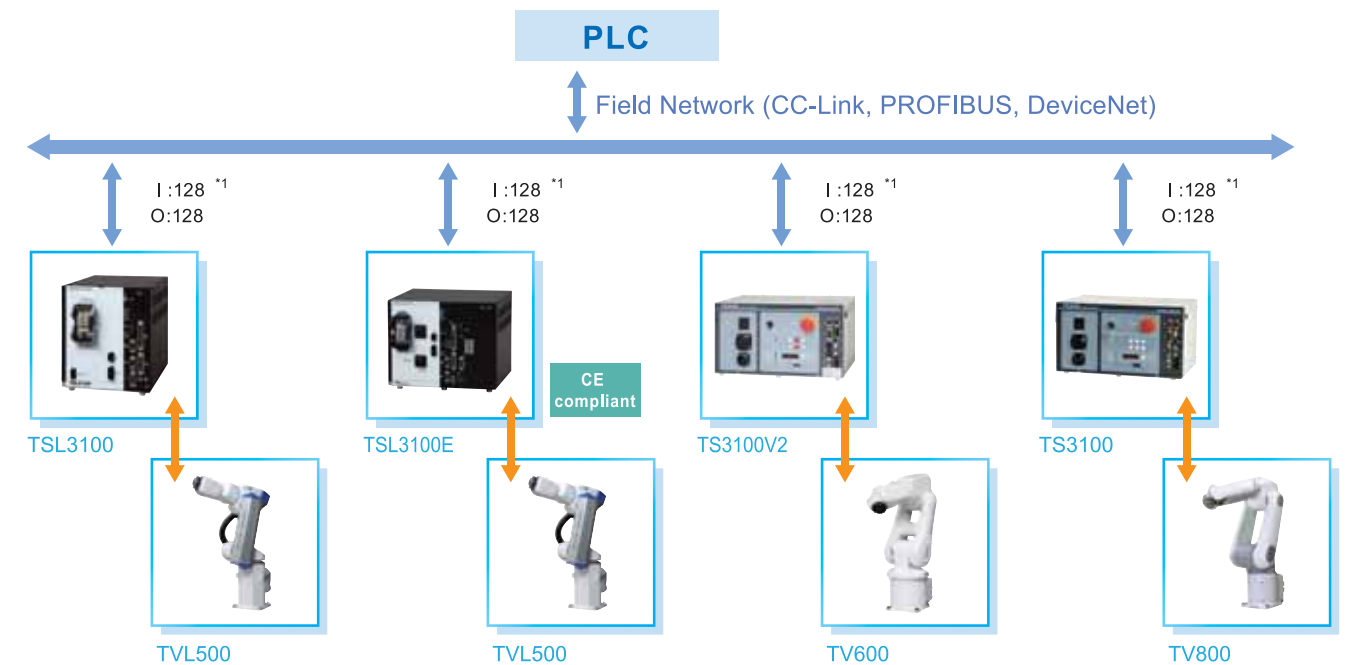
#### [Features and Advantages]

- TCmini controls input/output signals of standard I/O, extension I/O and touch-sensitive panel by a ladder program and exchanges data with the robot program.
- By changing the ladder program, system I/O signals can be used as standard I/O signals, and system I/O signals can be assigned as expansion I/O signals and field network I/O signals.
- Flexible system design and control of peripheral equipment are possible without the added cost of an outside host PLC.
- Creation, monitoring and debugging of a ladder program are possible with powerful programming support software "TCPRGOS-W" (optional).
- The scan time is 5ms per 1 K-Word (TSL3100). Connection is possible with various programmable controllers and display units etc.



## Field Network

Various field network protocols are supported.

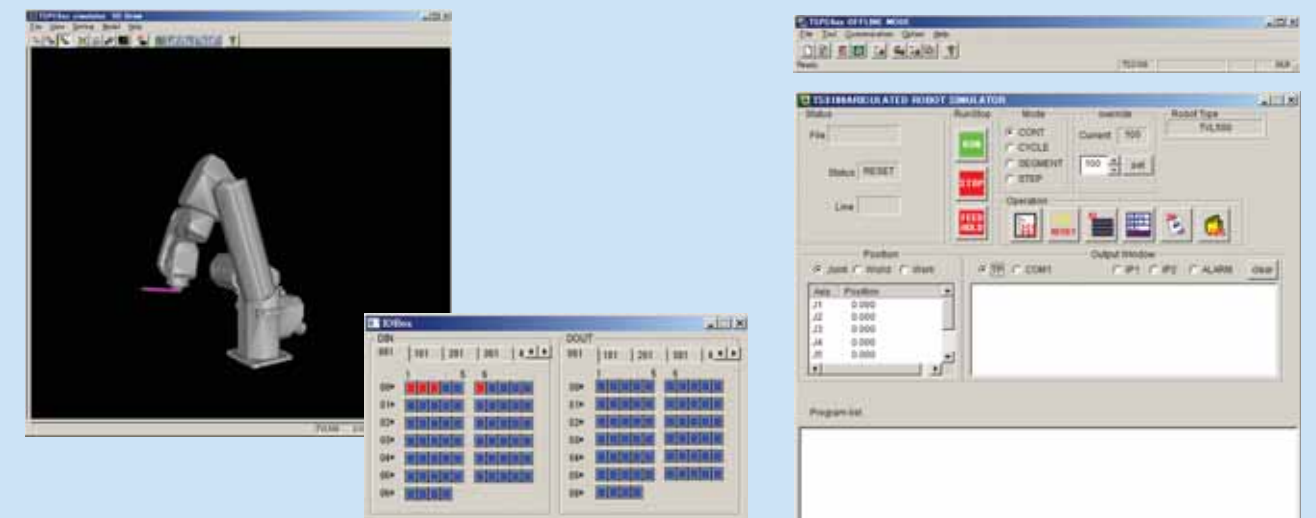


\*1: I:126 and O:126 for CC-Link

## PC Software for Programming Support

The following PC software tools are provided to shorten the time and increase the efficiency of system designing and installation work.

### TSPC: For robot programming



#### 1. Powerful simulation function

Off-line robot program creation and simulation, with simulated I/O. Lead time up to the start of robot operation can be shortened. Robot programs can be pre-checked without stopping the production line.

#### 2. User-friendly programming environment

Extensive help information, powerful grammar check, direct, online editing of programs in the controller memory.

#### 3. Multi-functional monitor and support

Monitoring functions such as active program display, position display, motion status monitor by 3D model, and alarm history display. Operation from on-screen operation panel. Connection via Ethernet (optional) is also supported.